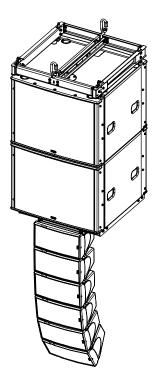
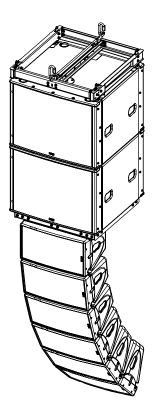
VNI-LNKM61018

DP5483 – 01b - DI

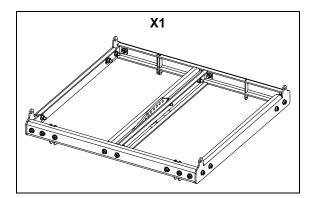


Adapter MSUB18-I to GEOM6 / GEOM10-I





Contents:



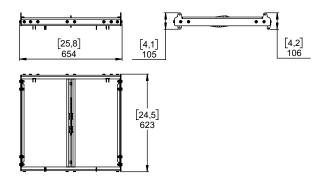
Weight: 11 kg / 22 lb



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Dimensions:



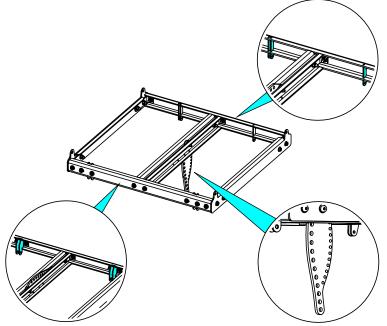
WARNING:

Max: $N_{GEOM10} + 1.5N_{MSUB18} \le 12 / N_{GEOM6} + 1.5N_{MSUB18} \le 12$

Use NEXO Simulation Software for mechanical prediction

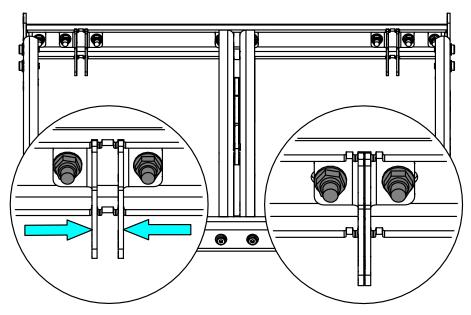
Equipment

A side with rigging for GEOM6, and another side for GEOM10. A LinkBar allows you to connect the rear of the box.



Configuration for GEOM10 left or right

Adjust RigLink for GEOM10, untight the screws, move the RigLinks.





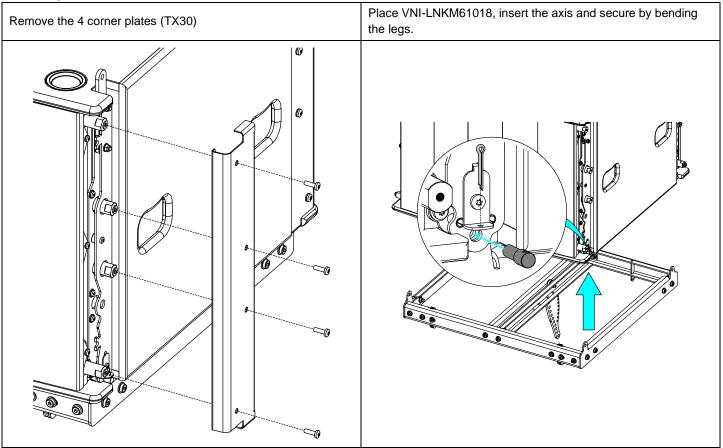
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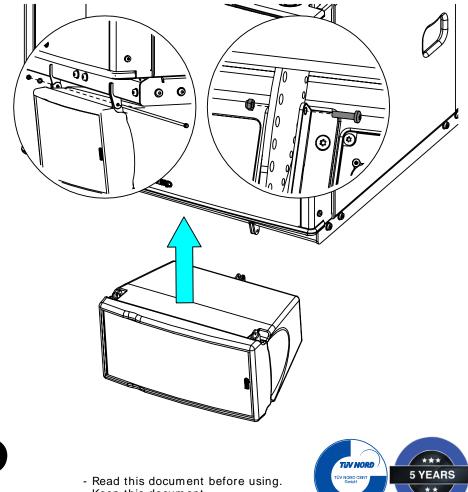
Assembly on MSUB18-I:



Assembly with GEOM6 and GMI-BNFIX (6x GEOM6 max):

Insert the axis and the washers (M5) and secure with the brake nuts (M5).

Adjust the appropriate inter-angle value with the Hybrid LinkBar and secure with provided screws.

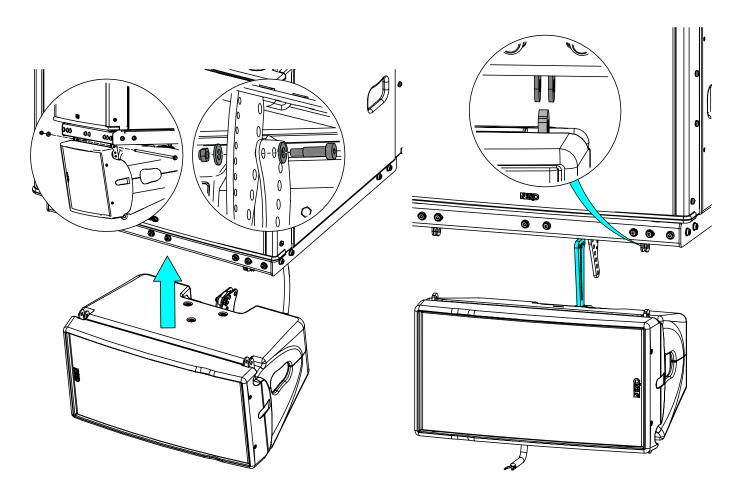




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Assembly with GEOM10-I (6x GEOM10 max):

Insert the axis and the washers (M8) and secure with the brake nuts (M8). Adjust the appropriate inter-angle value with the Hybrid LinkBar and secure with provided screws. For left configuration (HF waveguide is left), remove the LinkBar of the first GEOM10-I (see right picture).



Inter-angle with the first GEOM6 or GEOM10.				
Seo M <u>6</u>	$Z \bigcirc \bigcirc Z \\ X \bigcirc \bigcirc \bigcirc Z \\ U \bigcirc \bigcirc \bigcirc X \\ V \bigcirc \bigcirc \bigcirc V \\ V \bigcirc \bigcirc \bigcirc V \\ T \bigcirc \bigcirc \triangleleft \bigcirc V \\ U \bigcirc \bigcirc V \\ U \bigcirc \bigcirc V \\ U \bigcirc O \\ V \\ V \bigcirc \bigcirc V \\ U \bigcirc V \\ S \bigcirc \bigcirc O \\ R \\ M \bigcirc \bigcirc O \\ P \\ \bigcirc \\ O \\ M \\ \bigcirc M \\ O \\ O \\ M \\ O \\ O$	Seo M10	MARK	Angle
			Z	+15°
			X	+12°
			V	+9°
			U	+6°
			Т	+3°
			S	0 °
			R	-3°
			Q	-6°
			Р	-9°
			Ν	-12°
			Μ	-15°

- NEXO cannot accept responsibility for accidents caused by any factor other than defects in this product itself.
- Please check the web site <u>nexo-sa.com</u> for the latest update.



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